Amendments to the Claims

This listing of claims will replace all prior versions, and listings, of claims in the application:

1-39. (Cancelled)

40. (Previously Presented) A method for exception reporting in a vehicle management system, comprising:

receiving data corresponding to a parameter of the vehicle;

determining whether the data corresponding to the parameter is outside a range of acceptable values;

if the data corresponding to the parameter is outside a range of acceptable values, noting an exception;

wherein the parameter comprises a length of time the vehicle is in motion; and;

wherein the length of time the vehicle is in motion is referred to as windshield time.

41. (Previously Presented) A method for exception reporting in a vehicle management system, comprising:

receiving data corresponding to a parameter of the vehicle;

determining whether the data corresponding to the parameter is outside a range of acceptable values;

if the data corresponding to the parameter is outside a range of acceptable values, noting an exception; and

wherein the parameter comprises travel distance.

42. (Previously Presented) A method for exception reporting in a vehicle management system, comprising:

receiving data corresponding to a parameter of the vehicle;

determining whether the data corresponding to the parameter is outside a range of acceptable values;

if the data corresponding to the parameter is outside a range of acceptable values, noting an exception; and

wherein the parameter comprises vehicle speed.

43-51. (Cancelled)

52. (Previously Presented) A vehicle monitoring system, comprising:

a receiver for receiving vehicle location information;

a processor in communication with the receiver;

the processor programmed to perform a comparison of the vehicle location information to a predefined parameter and to note an exception based on the comparison; and

wherein the predefined parameter comprises a desired location and the exception comprises a state wherein the vehicle is beyond a predetermined distance from the desired location.

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53. (Previously Presented) A vehicle monitoring system, comprising:

a receiver for receiving vehicle location information;

a processor in communication with the receiver,

the processor programmed to perform a comparison of the vehicle location

information to a predefined parameter and to note an exception based on the comparison;

and

wherein the predefined parameter comprises a restricted region and the exception

comprises a state whereby the vehicle is within a predetermined distance of the restricted

region.

54. ((Previously Presented) A vehicle monitoring system, comprising:

a receiver for receiving vehicle location information;

a processor in communication with the receiver,

the processor programmed to perform a comparison of the vehicle location

information to a predefined parameter and to note an exception based on the comparison;

and

wherein the predefined parameter comprises a predetermined speed and the

exception comprises a state whereby the vehicle is traveling at a speed greater than the

predetermined speed.

55. (Cancelled)

56. (Previously Presented) A vehicle monitoring system, comprising:

a receiver for receiving vehicle location information;

a processor in communication with the receiver,

the processor programmed to perform a comparison of the vehicle location information to a predefined parameter and to note an exception based on the comparison; and

further comprising a report generator for generating reports listing any noted exception.

57. (Previously Presented) A vehicle monitoring system, comprising:

a receiver for receiving vehicle location information;

a processor in communication with the receiver,

the processor programmed to perform a comparison of the vehicle location information to a predefined parameter and to note an exception based on the comparison; and

wherein the receiver is in further communication with an ignition sensor.

58. (Previously Presented) A vehicle monitoring system, comprising:

a receiver for receiving vehicle location information; and

a processor in communication with the receiver,

the processor programmed to determine the length of time the vehicle remains stationary, compare the length of time the vehicle remains stationary to a predetermined stationary time, and if the length of time the vehicle remains stationary is greater than or equal to the predetermined stationary time, then note an exception.

59. (Cancelled)

60. (Previously Presented) A system comprising:

a remote unit comprising a Global Positioning System receiver and a processor in communication with the Global Positioning System receiver; and

a memory in communication with the remote unit,

wherein the remote unit receives Global Positioning System data and uses the Global Positioning System data to generate an actual value for a predetermined parameter, and wherein the remote unit compares the actual value to a plurality of acceptable values for the predetermined parameter, and wherein the remote unit notes in memory if the actual value does not equal one of the plurality of acceptable values for the predetermined parameter.

61. (Previously Presented) The system according to claim 60, wherein the remote unit communicates with an ignition sensor of a vehicle.

62. (Previously Presented) The system of claim 61, wherein the processor receives a signal from the ignition sensor, determines a location of the vehicle, retrieves a time, and stores the time as a start of a shift time.

63. (Previously Presented) The system according to claim 62, further comprising designating a service center location for receiving information from the remote unit.

64. (Previously Presented) The system according to claim 62, wherein the processor compares an actual start of shift time to a predetermined range of start of shift times, and if the actual start of shift time falls outside the predetermined range of start of shift times, the processor notes an exception.

65. (Previously Presented) The system according to claim 60, wherein the predetermined parameter is speed and the actual value is an actual speed of the remote unit.

66. (Previously Presented) The system according to claim 60, wherein the predetermined parameter is stationary time and the actual value is a duration of remote unit stationary time.

67. (Previously Presented) The system according to claim 60, wherein the predetermined parameter is a number of times the remote unit is within a predetermined proximity to a service location and the actual value is an actual number of times the remote unit is within the predetermined proximity to the service location.

68. (Previously Presented) The system according to claim 60, wherein the predetermined parameter is windshield time, and the actual value is actual windshield time.

69. (Previously Presented) The system according to claim 60, wherein the predetermined parameter is distance over a period of time, and the actual value is an actual distance traveled by the remote unit over the period of time.

70. (Previously Presented) The system according to claim 60, wherein the remote unit detects a loss of reception of Global Positioning System data and stores information associated with the loss of reception.

71. (Previously Presented) A system comprising:

a remote unit comprising a Global Positioning System receiver, a processor in communication with the Global Positioning System receiver and in communication with a memory, wherein the remote unit uses the Global Positioning System data to determine an actual speed of the remote unit, compares the actual speed to a predetermined upper speed limit, and notes an exception if the actual speed is greater than the predetermined upper speed limit.

72. (Previously Presented) The system of claim 71, wherein the remote unit notes an exception if the actual speed equals the predetermined upper speed limit.

73. (Previously Presented) The system according to claim 71, further comprising using the Global Positioning System data to determine a duration of remote unit stationary time and comparing the duration of remote unit stationary time to a predetermined stationary time threshold, and if the actual duration of remote unit

stationary time is greater than the predetermined stationary time threshold, the processor

notes an exception.

74. (Previously Presented) The system of claim 73, wherein the processor notes

an exception if the actual duration of remote unit stationary time equals the

predetermined stationary time threshold.

75. (Previously Presented) The system according to claim 71, further comprising

generating where at least one report.

76. (Previously Presented) The system according to claim 71, wherein the

processor notes if the actual speed is greater than the predetermined upper speed limit by

generating a report that includes information related to instances where the actual speed

is greater than the predetermined upper speed limit.

77-80. (Cancelled)

81. (Previously Presented) A system comprising:

a remote unit comprising a Global Positioning System receiver, wherein the

remote unit receives Global Positioning System data and uses the Global Positioning

System data to generate an actual value for a predetermined parameter, and wherein the

remote unit compares the actual value to a plurality of acceptable values for the

predetermined parameter, and wherein the remote unit records an exception if the actual

value does not equal one of the plurality of acceptable values for the predetermined parameter.

82. (Previously Presented) The system according to claim 81, wherein the predetermined parameter is speed and the actual value is an actual speed of the remote unit.

83. (Previously Presented) A method for monitoring a vehicle comprising:

receiving Global Positioning System data at a remote unit of the vehicle;

using the Global Positioning System data to generate an actual value for a predetermined parameter;

comparing the actual value to a plurality of acceptable values for the predetermined parameter; and

noting an exception if the actual value does not equal one of the plurality of acceptable values for the predetermined parameter.

84. (Previously Presented) The method according to claim 83, wherein the predetermined parameter is speed and the actual value is an actual speed of the remote unit.

85. (Previously Presented) The method according to claim 83, wherein the predetermined parameter is stationary time and the actual value is an actual duration of remote unit stationary time.

86. (Previously Presented) A method for monitoring a vehicle with a remote Global Positioning System receiver, comprising:

receiving Global Positioning System data to determine an actual speed for the vehicle;

comparing the actual speed to a predetermined upper speed limit; and

noting an exception if the actual speed is greater than the predetermined upper speed limit.

87. (Previously Presented) The method of claim 86, wherein an exception is noted if the actual speed equals the predetermined upper speed limit.

88. (Previously Presented) The method according to claim 86, wherein the Global Positioning System data is used to determine an actual duration of remote unit stationary time and the actual duration of remote unit stationary time is compared to a predetermined stationary time threshold, and if the actual duration of remote unit stationary time is greater than the predetermined stationary time threshold, noting an exception.

89. (Previously Presented) The method of claim 88, further comprising noting an exception if the actual duration of remote unit stationary time equals the predetermined stationary time.

90. (Previously Presented) The method of claim 86, further comprising generating at least one report.

91. (Previously Presented) The method of claim 86, further comprising noting if the actual speed is greater than the predetermined upper speed limit by generating a report that includes information related to instances where the actual speed is greater than the predetermined upper speed limit.